

# 5. Column generation

Lec 9, 10.1.13

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rough idea: suppose we have an LP with a huge number of variables, let's ignore some of them and add them later.

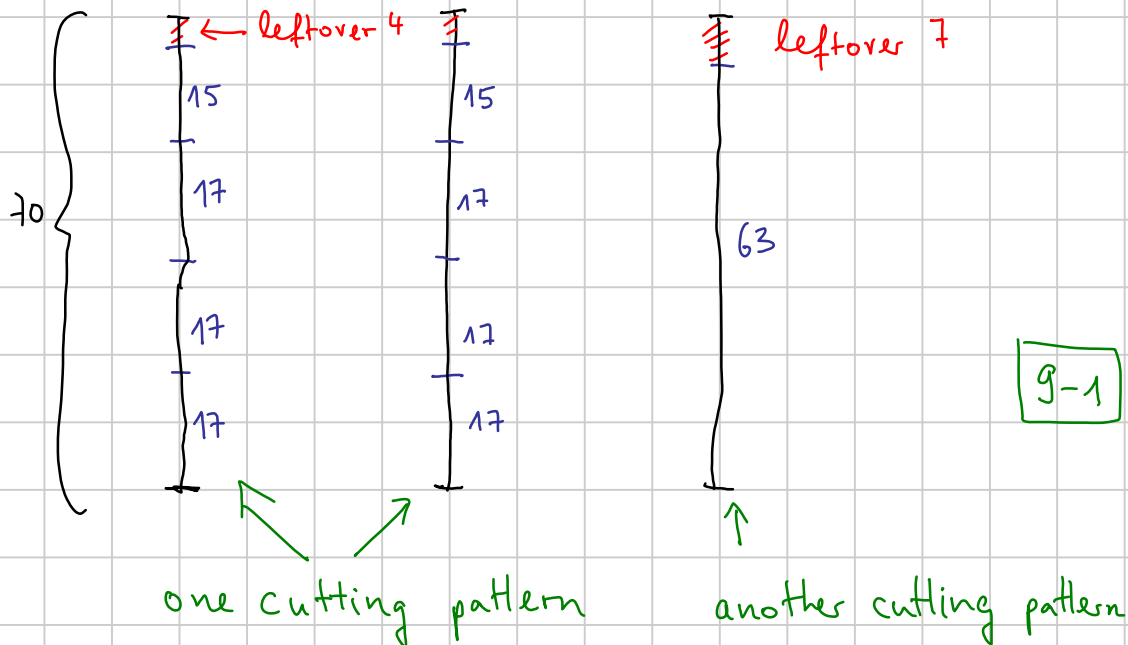
## Example 5.1 Cutting stock problem (CSP)

- given:
- supply of long tubes, (or rolls of paper) each of length  $W \in \mathbb{N}$
  - demand:  $d_i \in \mathbb{N}$  short tubes of length  $w_i \leq W$  for  $i \in [n]$
  - where short tubes must be cut out of long tubes

minimize: • number of long tubes needed

e.g.:  $W = 70, w_1 = 17, d_1 = 6$   
 $w_2 = 15, d_2 = 2$   
 $w_3 = 63, d_3 = 1$

a feasible solution:



A cutting pattern is a vector  $x \in \mathbb{N}_0^n$ ,  
 where  $x_i$  denotes the number of short  
 tubes of length  $w_i$  cut out of a long tube.

$$\text{feasibility: } \sum_{i=1}^n x_i w_i \leq W$$

$$\text{number of long tubes needed} \leq \sum_{i=1}^n d_i =: K$$

define  $y \in \{0,1\}^K$  where for  $k \in K$   
 $y_k = 1$  iff  $k$ -th long tube is needed

$$\rightarrow \text{goal: minimize } \sum_{k=1}^K y_k$$

For the  $k$ -th long tube denote by  $x^k \in \mathbb{N}_0^n$   
 the (unknown) cutting pattern

$$\rightarrow \text{feasibility: } \sum_{i=1}^n x_i^k w_i \leq W \cdot y_k \quad \forall k \in K$$

$$\rightarrow \text{demands: } \sum_{k=1}^K x_i^k \geq d_i \quad \forall i \in [n]$$

$$\underline{\text{ILP}}_1: \left\{ \begin{array}{l} \min_{y, x} \sum_{k=1}^K y_k : y \in \{0,1\}^K \end{array} \right.$$

$$x^k \in \mathbb{N}_0^n \quad \text{for } k=1, \dots, K$$

$$\sum_{k=1}^K x_i^k \geq d_i \quad \text{for } i=1, \dots, n$$

$$\sum w_i x_i^k \leq W y_k \quad \text{for } k=1, \dots, K$$

advantage: small number of variables  
 and constraints

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but: gap between  $\text{ILP}_1$  and LP-relaxation  
 can be big.

Prop. 5.2 Consider the LP-relaxation  $LP_1$  of  $ILP_1$ , where  $x_i^k, y_k \in \mathbb{R}$ .

Then its optimal value is  $\frac{\sum_{i=1}^n w_i d_i}{W}$ .  
(number of long tubes)

Proof: obvious.

Example 5.3  $n := 1$   
 $d_1$  arbitrary  
 $w_1 := \lfloor \frac{W}{z} \rfloor + 1$

Then optimal value of  $ILP_1$  is  $d_1$ ,  
but by Prop 5.2 the optimal value of  $LP_1$  is

$$\frac{d_1 w_1}{W} = \frac{d_1 (\lfloor \frac{W}{z} \rfloor + 1)}{W} \approx \frac{d_1}{z}$$

$\leadsto$  big gap.

Example 5.4 We try a second ILP-formulation

$Q :=$  set of all valid cutting patterns  
 $Q = \{ x^j : j = 1, \dots, |Q| \}$ . (This is a huge set.)

Let  $\mu_j \in \mathbb{N}_0$  denote how often pattern  $x^j \in Q$  is used.

$$\underline{\text{ILP}_2}: \quad \left\{ \begin{array}{l} \min \sum_{j=1}^{|\mathcal{Q}|} p_j : p_j \in \mathbb{N}_0 \quad \forall j=1, \dots, |\mathcal{Q}| \\ \sum_{j=1}^{|\mathcal{Q}|} x_i^j p_j \geq d_i \quad \forall i=1, \dots, n \end{array} \right\}$$

(Master problem)

Here we think of the set  $Q = \{x^j : j \in [|\mathcal{Q}|]\}$  as given. We know that

$$\text{(subproblem)} \quad Q = \left\{ x \in \mathbb{N}_0^n : \sum_{i=1}^n w_i x_i \leq W \right\}.$$

Column generation approach to solve ILP<sub>2</sub>:

Start with the master problem over a small subset of  $Q$  and solve it. If this solution is not optimal for the original problem (how do we check this?), generate additional cutting patterns from  $Q$  (which?).

To answer the two blue questions, we first recall basic facts about the simplex method.

$$\text{LP:} \quad \max \{ c^T x : Ax = b, x \geq 0 \}$$

$$A \in \mathbb{R}^{m \times n}, \quad b \in \mathbb{R}^m, \quad c \in \mathbb{R}^n$$

$$\left. \begin{array}{l} B = (p_1, \dots, p_m) \in [n]^m \\ N = (q_1, \dots, q_{n-m}) \in [n]^{n-m} \end{array} \right\} \begin{array}{l} \text{vectors with} \\ \text{column indices} \end{array}$$

such that  $\{p_1, \dots, p_m\} \cup \{q_1, \dots, q_{n-m}\} = [n]$ .

Denote by  $A_B$  and  $A_N$  the submatrices of  $A$  consisting of the columns of  $A$ , indexed by the indices in  $B$  and  $N$ .

If  $A_B$  regular, then  $(A_B, A_N)$  is called a basis  
 $x$  defined by  $x = (x_B, x_N)$  with

$$x_B := A_B^{-1} b \quad \text{and} \quad x_N := 0$$

is called the corresponding basis solution.

Then

$$c^T x = c_B^T A_B^{-1} b + \underbrace{(c_N^T - c_B^T A_B^{-1} A_N)}_{\substack{\\ // \\ c^T}} x_N$$

reduced costs:

If  $\bar{c} \leq 0$ , then the basis solution is optimal.

If  $\bar{c}_j > 0$ , then the  $j$ -th column of  $A_N$   
should enter the basis.

### Column generation and simplex method:

$$LP: \max \{ c^T x : Ax \leq b, x \geq 0 \}$$

Let  $A'$  consist of, say, the first  $n'$   
columns of  $A$ , shrink  $x$  to  $x'$  and  $c$  to  $c'$   
accordingly.

$$LP': \max \{ c'^T x' : A' x' \leq b, x' \geq 0 \}$$

Let  $x^{*'}$  be an optimal solution of  $LP'$   
with basis  $(A'_B, A'_N)$ .

Then  $(x^{*'}_B, 0)$  is feasible for  $LP$   
and defines a feasible basis  $(A_B, A_N)$   
which may or may not be optimal for  $LP$ .

Check this by looking at the reduced cost

$$\bar{c}^T := c_N^T - c_B^T A_B^{-1} A_N$$

A column in  $A_N$  with positive reduced costs is a candidate to enter the basis for LP.

We find the best such candidate by taking the one with largest reduced costs by solving the

pricing problem:  $\max \{ c_j - y_B^T a^j : a^j \text{ is a column of } A_N, j \text{ the corresponding index} \}$

where  $y_B^T := c_B^T A_B^{-1}$ .

Suppose we can solve the pricing problem efficiently (i.e. without looking at all the columns).

Then this gives us the column with the largest reduced costs, add it to  $A'$  and iterate.

Stop when  $\bar{c} \leq 0$ , because we have then found an optimal solution.

What does the pricing problem look like in our ILP<sub>2</sub> - case?

Let  $A_B'$  be an optimal basis of the current (related) master problem.

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Then a column of  $A_N$  is just a

feasible cutting pattern, i.e. a vector  $x \in \mathbb{N}_0^n$  satisfying the constraints from the subproblem:

$$\sum_{i=1}^n w_i x_i \leq W.$$

Hence the pricing problem becomes

$$\min \left\{ 1 - y_B^T x : \sum_{i=1}^n w_i x_i \leq W, x \in \mathbb{N}_0^n \right\}$$

because CSP  
is a min!-problem

$$\text{where } y_B^T := c_B^T A_B^{-1}$$

and this is (nothing but a good old) Knapsack problem.

Although Knapsack is NP-hard, it is usually well-behaved and can be solved efficiently in practice (dyn. progr., approximation; see Lectures 2 and 3).

Also note that  $n \ll |Q|$ ,  
so we have reduced the complexity a lot.